

ELECTRONIC POWER STEERING TROUBLESHOOTING MANUAL

*please read before contacting customer support

EPS Trouble Shooting Procedures

- **I.** Unplug and re-plug all connectors. According to Installation Manual, make sure connections are correct.
- II. Check if the fuse is blown out.



III. Check the light pattern which can help us narrow the issue to a specific component

Start the vehicle and view the LED Diagnostic Light, the light should turn on for one second then turn off, if the light remains on you have an incorrect connection in the system, please refer to Electronic Fault Diagnosis Table.



If there is a malfunction with an electronic part, the system will create a code to identify the problem. Each fault code is displayed by a series of flashes with through the fault light.

- **IV.** If the light pattern does not indicate the fault code
 - a. Check the power supply wire. There should be three wires, red (positive), black (negative) and white (switch). Make sure all wires are working.
 - b. Check the voltage of sensor seat by multimeter.
 - i. Set the selection knob in DC range. Connect the black probe to the ground wire of the sensor seat (green wire). Connect the red probe to the positive wire of the sensor seat (orange wire). If the multimeter has no reading, the problem should be the ECU. The reading of the multimeter should be 5V.
 - ii. Check the main torque sensor. Connect the red probe to the main torque sensor wire (white wire). Connect the black probe to the ground wire of the sensor seat (green wire). The reading of the multimeter should be 2.5 V to indicate the main torque sensor is working.

- iii. Check the vice torque sensor, Connect the black probe to the ground wire of the sensor seat (green wire). Connect the red probe to the vice torque sensor wire (black wire). The reading of the multimeter should be 2.5 V to indicate the vice torque sensor is working.
- c. Check the voltage of the Motor seat
 - Set the selection knob in DC range. Connect the black probe to the ground wire of the motor seat (black wire). Connect the red probe to the positive wire of the motor seat (red wire). The reading of the multimeter should be 12 V to indicate the motor is working.

If all above seats work properly, the problem is with the ECU.

Every fault code is composed of double digits, Each long flash represents a multiple of 10 and is 2 seconds in length and each short flash represents a single digit and is 1 seconds in length. There will be a 3 seconds space between the long flashes and the short flashes.

For example: long flash\long flash \space\short flash represents the code number 21.

Example:



Code	Diagnosis content	fault code wave
21	Main torque sensor disconnection	
22	Main torque sensor output error(voltage is too high or low)	
23	Vice torque sensor disconnected	
24	Vice torque sensor output error(voltage is too high or low)	
25	Main and vice torque difference is too large	
26	Main torque sensor inner fault	
35	Current sensor zero offset is too large	
32	Motor disconnected	
33	Current of ECU is over the limit	
34	One side of motor has no assistance	
36	Motor voltage abnormal	

Code 21-24: Sensor Problems

Code	Diagnosis Content	Possible Reasons	Rate	Suggestions	Solutions
21	Main torque sensor disconnection	The main torque sensor wire	1. Sensor fault: 80%	Unplug and re-plug all wires. Turn the	1. Plug all wire
22	Main torque output error (voltage is too high or low)	(white) disconnected. 2. The vice torque	2. Sensor seat has bad contact: 17%	steering wheel, see if the problem still exist or not.	properly. 2. Replace ECU
23	Vice torque sensor disconnection	sensor wire (black)	3. Pseudo solder: 3%	Check the voltage of each wire by	3. Change Motor
24	Vice torque output error (voltage is too high or low)	disconnected. 3. The voltage	3014611374	multimeter (see IV.b for detail).	ete:
25	Main and vice torque difference is too large	difference between ground wire (green) and main/vice torque sensor wire is too large. 4. There is open circuit in main or vice torque sensor		3. Test with new ECU	

Code 26-35: ECU Problems

Code	Diagnosis Content	Possible Reasons	Rate	Suggestions	Solution
26	Main torque sensor	Motor disconnect	35%	Check the motor. If motor	Replace the
	inner fault	ECU damaged		is good, test with new	motor
				ECU	Replace ECU
32	Motor disconnected	ECU damaged	5%	Test with new ECU	Replace ECU
34	One side of motor has	ECU damaged	25%	Test with new ECU	Replace ECU
	no assistance				
35	Current sensor zero	ECU damaged	5%	Test with new ECU	Replace ECU
	offset is too large				

System Trouble Shooting

No.	Failure	Possible Reason	Troubleshooting	
	Encountered			
1.	Steering without	1. Connectors of wire have bad	1. Check whether wire connectors	
	assistance	contact	are fully inserted	
		2. The fuse is burnt out	2. Replace the fuse (30A)	
		3. Relay damage	3. Replace the relay	
		4. The ECU, motor or sensor is	4. Replace the motor or the sensor	
		damaged		
2.	Steering with	 Misconnection between power 	1. Connect all wire correctly	
	inconsistent	supply wire and switch wire	2. Unplug and re-plug all wires	
	assistance	2. Switch wire have bad contact	3. Replace ECU	
		3. ECU has Pseudo solder		
3.	System has noise	1. Motor damaged	1. Replace motor	
		2. Gap of lower steering shaft	2. Replace assembly	
		assembly or mechanical steering	3. Check whether the installation	
		assembly is too large	screw is tight, adjust	
		3. Installation of lower steering	4. Check whether the universal	
		shaft assembly or mechanical	joint and connecting shaft	
		steering assembly loose	interfere each other	
4.	Steering is not	1. The parameter of the sensor is	1. Replace the motor	
	accurate	abnormal	2. Inflate tires	
		2. The air pressure of front tires is	3. Replace the ECU	
		abnormal		
		3. ECU damaged		
5.	Steering	Battery power loss	1. Charge battery	
	becomes heavy	2. Motor damaged (power	2. Contact with suppliers and	
		reduction)	replace it	
		3. Air pressure of the tires (front) is	3. Inflate tires	
		insufficient		
		4. Thermal protection		
6.	The vehicle	1. The swing arm or tie rod is	1. Replace the swing arm or tie rod	
	swings on both	damaged		
<u> </u>	sides			
7.	When system is	Motor is mounted backwards	Reverse the motor seat and plug	
	on, the steering	2. ECU or sensor is damaged	in in correct order	
	wheel swings on both sides	3. Resistor has bad contact	2. Replace the ECU	
8.	Stuck in	There is interferer in shaft	Adjust the distance between the	
0.	somewhere	assembly	lower shaft and rack and pinion	
	when steering			
	When seeing		2. When installation, tight the first and third screw first. Then rotate	
		match with steering tube		
		3. Motor damaged	the steering wheel left and right,	

			3.	free the lower steering shaft. Then, tight the second screw Replace the motor
9.	There is strong rebounding force when turn the steering wheel to full lock	The parameter of sensor over the range of ECU	1.	Replace the ECU
10.	Power is not the same for left and right	 The median output voltage has deviation ECU, motor or sensor is damaged 	2.	loosen the sensor adjustment screw, adjust the sensor position to keep the voltage in 1.65V ± 0.05V

System Cautions

In order to ensure the performance of the steering system, and improve the life of the steering system, we must insist on strict compliance with the following rules:

- 1. Do not dismantle the control box because you can create an imbalance between the power to the right and left steering.
- 2. Maintain good battery, loss of battery power will result in heavy steering.
- 3. Pack all electrical connections with dielectric grease where possible to help against corrosion especially in damp humid conditions.
- 4. Do not tap into the EPS electrical harness for any other aftermarket components.
- 5. Connector of the system must be in good contact.
- 6. The controller must not be near high temperatures and protected from moisture.
- 7. When steering your machine and reaching maximum turn angle, do not hold that maximum position for longer than 3 seconds to ensure you do not overheat the electric motor and controller.
- 8. When motor is working, you must not insert or extract the connector of controller, motor and sensor.